ON THE WEAKLY DAMPED VIBRATIONS OF A STRING ATTACHED TO A SPRING-MASS-DASHPOT SYSTEM

DARMAWIJOYO$^{1,2}$ AND W.T. VAN HORSSEN$^2$

Abstract. In this paper an initial-boundary value problem for a homogeneous string (or wave) equation is considered. One end of the string is assumed to be fixed and the other end of the string is attached to a spring-mass-dashpot system, where the damping generated by the dashpot is assumed to be small. This problem can be regarded as a simple model describing oscillations of flexible structures such as overhead power transmission lines. A semigroup approach will be used to show the well-posedness of the problem as well as the asymptotic validity of formal approximations of the solution on long time-scales. A multiple time-scales perturbation method will be used to construct asymptotic approximations of the solution. Although the problem is linear the construction of these approximations is far from being elementary because of the complicated, non-classical boundary condition.

Key words. wave equation, boundary damping, semigroup, asymptotics, two-timescales perturbation method.

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1. Introduction

There is a number of examples of flexible structures such as suspension bridges, overhead transmission lines, dynamically loaded helical springs that are subjected to oscillations due to different causes. Simple models which describe these oscillations can be expressed in initial-boundary value problems for wave equations like in [4,5,8,11,14] or for beam equations like in [1,9,10,15].

In most cases simple, classical boundary conditions are applied (such as in [1,4,8]) to construct approximations of the oscillations. For more complicated, non-classical boundary conditions (see for instance [5,6,10,11,14,15]) it is usually not possible to construct explicit approximations of the oscillations. In this paper we will study such an initial-boundary value problem with a non-classical boundary condition and we will construct explicit asymptotic approximations of the solution, which are valid on a long time-scale. We will consider a string which is fixed at $x = 0$ and attached to a spring-mass-dashpot system at $x = 1$ (see also figure 1.1).

![Figure 1.1. A simple model of a string fixed at $x = 0$ and attached to a spring-mass-dashpot system at $x = 1$.](image-url)

It is assumed that $\rho$ (the mass-density of the string), $T$ (the tension in the string), $\tilde{m}$ (the mass in the spring-mass-dashpot system), $\tilde{\gamma}$ (the stiffness of the spring), and $\tilde{\epsilon}$ (the damping coefficient of the dashpot with $0 < \tilde{\epsilon} \ll 1$) are all positive constants. Furthermore, we only

$^1$On leave from State University of Sriwijaya, Indonesia (darma@dv.twi.tudelft.nl).
$^2$Department of Technical Mathematics and Informatics, Delft University of Technology, P.O. Box 5031, 2600 GA Delft, The Netherlands (w.t.vanhorssen@dv.twi.tudelft.nl).
consider the vertical displacement $\bar{u}(x, \bar{t})$ of the string, where $x$ is the place along the string, and $\bar{t}$ is time. Gravity and other external forces are neglected.

After applying a simple rescaling in time and in displacement ($\bar{t} = \sqrt{\frac{\rho}{m}} t$, $\bar{u}(x, \bar{t}) = u(x, t)$; putting $\bar{m} = \rho m$, $\bar{\gamma} = \gamma T$, and $\bar{\epsilon} = \sqrt{T \bar{m}}$) we obtain as a simple model for the oscillations of the string the following initial-boundary value problem

\begin{align}
(1.1) & \quad u_{tt} - u_{xx} = 0, \quad 0 < x < 1, \ t > 0, \\
(1.2) & \quad u(0, t) = 0, \ t \geq 0, \\
(1.3) & \quad mu_{tt}(1, t) + \gamma u(1, t) + u_x(1, t) = -\epsilon u_t(1, t), \ t \geq 0, \\
(1.4) & \quad u(x, 0) = \phi(x), \ 0 < x < 1, \\
(1.5) & \quad u_t(x, 0) = \psi(x), \ 0 < x < 1,
\end{align}

where $m$ and $\gamma$ are positive constants, and where $\epsilon$ is a small parameter with $0 < \epsilon \ll 1$. The functions $\phi$ and $\psi$ represent the initial displacement of the string and the initial velocity of the string respectively.

In this paper we will prove the well-posedness of the initial-boundary value problem (1.1) - (1.5), and we will construct explicit, asymptotic approximations of the solution up to order $\epsilon$ on a time-scale of order $\epsilon^{-1}$. This paper is organized as follows. In section 2 we first study the undamped initial - boundary value problem (1.1) - (1.5) with $\epsilon = 0$. In section 3 of this paper a boundedness property of the solution is discussed. By using a semigroup approach we show in section 4 that for $0 < \epsilon \ll 1$ the problem (1.1) - (1.5) is well-posed for all $t \geq 0$. In section 5 a formal approximation of the solution of (1.1) - (1.5) is constructed using a multiple timescales perturbation method. The asymptotic validity of this formal approximation will be proved in section 6 on a time-scale of order $\epsilon^{-1}$. Finally in section 7 some remarks will be made and some conclusions will be drawn.

2. THE UNDAMPED PROBLEM (1.1) - (1.5) WITH $\epsilon = 0$

In this section the method of separation of variables will be used to solve problem (1.1) - (1.5) with $\epsilon = 0$, that is,

\begin{align}
(2.1) & \quad u_{tt} - u_{xx} = 0, \quad 0 < x < 1, \ t > 0, \\
(2.2) & \quad u(0, t) = 0, \ t \geq 0, \\
(2.3) & \quad mu_{tt}(1, t) + \gamma u(1, t) + u_x(1, t) = 0, \ t \geq 0, \\
(2.4) & \quad u(x, 0) = \phi(x), \ 0 < x < 1, \\
(2.5) & \quad u_t(x, 0) = \psi(x), \ 0 < x < 1.
\end{align}

The solution of this problem will play an important role in section 5. We now look for a nontrivial solution of the PDE (2.1) and the BCs (2.2) - (2.3) in the form $X(x)T(t)$. By substituting this form into (2.1) - (2.3) we obtain a boundary value problem for $X(x)$:

\begin{align}
(2.6) & \quad -X''(x) = \lambda X(x), \\
(2.7) & \quad X(0) = 0, \\
(2.8) & \quad X'(1) = (m\lambda - \gamma)X(1),
\end{align}

and the following problem for $T(t)$:

\begin{align}
(2.9) & \quad -T''(t) = \lambda T(t).
\end{align}

First we show that the eigenvalues $\lambda$ of the eigenvalue-problem (2.6) - (2.8) are real and positive. A similar proof for problems with classical boundary conditions (such as Dirichlet, Neumann, or Robin conditions) can be found in [7]. Let $\lambda$ be an eigenvalue and $X(x)$ a corresponding eigenfunction satisfying $-X''(x) = \lambda X(x)$. Taking the complex conjugate of this equation we obtain $-X''(x) = \lambda X(x)$. So, $X(x)$ and $X(\bar{x})$ are eigenfunctions corresponding to the eigenvalues $\lambda$ and $\bar{\lambda}$ respectively. Now consider
\[ (2.10) \]
\[
\int_0^1 (-X''(x) \ddot{X}(x) + X(x) \dddot{X}(x)) \, dx = \left[ -X'(x) \ddot{X}(x) + X(x) \dddot{X}(x) \right]_{x=0}^1 = -m(\lambda - \bar{\lambda})X(1)\dddot{X}(1),
\]
and
\[ (2.11) \]
\[
\int_0^1 (-X''(x) \ddot{X}(x) + X(x) \dddot{X}(x)) \, dx = \int_0^1 (\lambda X(x) \dddot{X}(x) - \bar{\lambda} X(x) \dddot{X}(x)) \, dx = (\lambda - \bar{\lambda}) \int_0^1 X(x) \dddot{X}(x) \, dx.
\]

Subtracting (2.10) from (2.11) yields
\[ (2.12) \]
\[
(\lambda - \bar{\lambda}) \int_0^1 \left[ 1 + m \delta(x - 1) \right] X(x) \dddot{X}(x) \, dx = 0,
\]
where \( \delta(x - 1) = 0 \) for \( x \neq 1 \) and \( \int_0^1 \delta(x - 1) \, dx = 1 \). Since the integral in (2.12) is positive it follows that \( \lambda - \bar{\lambda} = 0 \). And so, \( \lambda \) is real. To prove that \( \lambda \) is positive we consider
\[ (2.13) \]
\[
\int_0^1 -X''(x) X(x) \, dx = -X(x) X'(x) \bigg|_{x=0}^1 + \int_0^1 (X')^2(x) \, dx
\]
\[ = -(m\lambda - \gamma) X^2(1) + \int_0^1 (X')^2(x) \, dx,
\]
and
\[ (2.14) \]
\[
\int_0^1 -X''(x) X(x) \, dx = \lambda \int_0^1 X^2(x) \, dx.
\]

Subtracting (2.13) from (2.14) yields
\[ (2.15) \]
\[
\lambda \int_0^1 \left[ 1 + m \delta(x - 1) \right] X^2(x) \, dx = \gamma X^2(1) + \int_0^1 (X')^2(x) \, dx.
\]

Since \( X(x) \) is an eigenfunction it follows that the integral in the left-hand side of (2.15) and that the right-hand side of (2.15) are both positive, and so \( \lambda > 0 \). In a completely similar way we can deduce that if \( \lambda_1 \) and \( \lambda_2 \) are two eigenvalues with corresponding eigenfunctions \( X_1(x) \) and \( X_2(x) \) respectively then
\[ (2.16) \]
\[
(\lambda_1 - \lambda_2) \int_0^1 [1 + m \delta(x - 1)] X_1(x) X_2(x) \, dx = 0.
\]

So, two different eigenfunctions belonging to two different eigenvalues are orthogonal with respect to inner product as defined by
\[ (2.17) \]
\[
< W_1(x), W_2(x) > = \int_0^1 \left[ 1 + m \delta(x - 1) \right] W_1(x) W_2(x) \, dx.
\]

The boundary value problem (2.6) - (2.8) for \( X(x) \) can now readily be solved, yielding
\[ (2.18) \]
\[
X(x) = A \sin(\sqrt{\lambda}x),
\]
where \( A \) is a constant and where \( \sqrt{\lambda} \) has to satisfy
\[ (2.19) \]
\[
\cot(\sqrt{\lambda}) = \frac{m\lambda - \gamma}{\sqrt{\lambda}}.
\]

It can be shown that (2.19) has infinitely many, isolated positive roots. We denote these roots by \( \lambda_n \), and it is clear that \( (n - 1)\pi < \sqrt{\lambda_n} < n\pi, \ n = 1, 2, 3, \cdots \). The differential
equation (2.9) for $T(t)$ can now also be solved. Finally we find as a nontrivial solution for
the PDE (2.1) and the BCs (2.2) - (2.3) with $\epsilon = 0$

$$u_n(x, t) = \left( A_n \cos(\sqrt{\lambda_n} t) + B_n \sin(\sqrt{\lambda_n} t) \right) \sin(\sqrt{\lambda_n} x),$$

where $\lambda_n$ satisfies (2.19), and where $A_n$ and $B_n$ are arbitrary constants. Using the super-
position principle we find as general solution of the PDE and BCs

$$(2.20) \quad u(x, t) = \sum_{n=1}^{\infty} \left( A_n \cos(\sqrt{\lambda_n} t) + B_n \sin(\sqrt{\lambda_n} t) \right) \sin(\sqrt{\lambda_n} x).$$

Using the initial values (2.4) - (2.5) and the inner product (2.17) we can determine the coefficients $A_n$ and $B_n$ in the general solution, yielding

$$(2.21) \quad A_n = \frac{\int_{0}^{1} [1 + m\delta(x - 1)] \phi(x) \sin(\sqrt{\lambda_n} x) \, dx}{\int_{0}^{1} [1 + m\delta(x - 1)] \sin^2(\sqrt{\lambda_n} x) \, dx},$$

and

$$(2.22) \quad B_n = \frac{1}{\sqrt{\lambda_n}} \frac{\int_{0}^{1} [1 + m\delta(x - 1)] \psi(x) \sin(\sqrt{\lambda_n} x) \, dx}{\int_{0}^{1} [1 + m\delta(x - 1)] \sin^2(\sqrt{\lambda_n} x) \, dx}.$$  

3. THE ENERGY OF THE STRING

In this section we will determine the energy of the string and we will show that the solution $u(x, t)$ of problem (1.1) - (1.5) is bounded if the initial energy is bounded. By multiplying the PDE (1.1) with $u_t(x, t)$ and by integrating the so-obtained equation with respect to $x$ from 0 to 1 we obtain

$$\frac{\partial}{\partial t} \int_{0}^{1} \left( \frac{1}{2} u_t^2(x, t) + \frac{1}{2} u_x^2(x, t) \right) \, dx = u_t(x, t) u_{xx}(x, t) \bigg|_{x=0}^{1}$$

$$= -mu_t(1, t) u_t(1, t) - \gamma u_t(1, t) u(1, t) - \epsilon u_t^2(1, t)$$

$$= - \frac{\partial}{\partial t} \left( \frac{1}{2} mu_t^2(1, t) + \frac{1}{2} \gamma u^2(1, t) \right) - \epsilon u_t^2(1, t).$$

By integrating this equation with respect to $t$ from 0 to $t$ we obtain the energy $E(t)$ of the string

$$E(t) = \int_{0}^{1} \left( \frac{1}{2} u_t^2(x, t) + \frac{1}{2} u_x^2(x, t) \right) \, dx + \frac{1}{2} mu_t^2(1, t) + \frac{1}{2} \gamma u^2(1, t)$$

$$= E(0) - \epsilon \int_{0}^{t} u^2_s(1, s) \, ds \leq E(0).$$  

(3.1)

It should be observed that the energy consists of the kinetic and the potential energies of the string and the mass. By using the Cauchy-Schwartz inequality it now follows that

$$|u(x, t)| = \left| \int_{0}^{t} u_s(s, t) \, ds \right| \leq \sqrt{\int_{0}^{t} u_s^2(s, t) \, ds} \leq \sqrt{2E(t)} \leq \sqrt{2E(0)}.$$  

(3.2)

And so, $u(x, t)$ is bounded if the initial energy is bounded.

4. WELL-POSEDNESS OF THE PROBLEM WITH BOUNDARY DAMPING

In this section we will show that the initial- boundary value problem (1.1) - (1.5) with $0 < \epsilon \ll 1$ is well-posed for all $t > 0$. To show the well-posedness we will use a semigroup approach.
Consider the following initial value problem
\begin{align}
\frac{dy(t)}{dt} &= Ay(t), \quad t > 0, \\
y(0) &= y_0.
\end{align}
Formally, \( y(\bullet) = T(\bullet) y_0 \), solves the initial value problem where \( A \) is the generator of \( T(t) \). Thus, from the point of view of solving initial value problems or abstract Cauchy problems, it is natural to ask, which operator \( A \) generates a \( C_0 \) semigroup \( T(t) \).

To prove the well - posedness of the initial - boundary value problem (1.1) - (1.5) we introduce the following auxiliary functions defined as follows;
\begin{align}
a(t) &= u(\bullet, t), \\
b(t) &= u_t(\bullet, t), \\
\eta(t) &= nu_t(1, t).
\end{align}
For simplicity, we denote \( a, b, \eta \) for \( a(t), b(t), \eta(t) \), respectively. Differentiating these functions with respect to \( t \) we obtain
\begin{align}
\begin{pmatrix}
a_t \\
b_t \\
\eta_t
\end{pmatrix}
&= \begin{pmatrix}
b \\
apx \\
\gamma a(1) + ap(1) + \frac{\omega}{m}\eta
\end{pmatrix}.
\end{align}
Next, we also define some function spaces, i.e;
\begin{align}
\mathcal{V} &= \{ a \in H^1[0, 1], a(0) = 0 \}, \\
\mathcal{H} &= \{ y(t) = (a, b, \eta) \in \mathcal{V} \times L^2[0, 1] \times \mathbb{R} \}.
\end{align}
Now we equip the space \( \mathcal{H} \) with the inner product
\begin{align}
\langle \cdot, \cdot \rangle : \mathcal{H} \times \mathcal{H} \to \mathbb{R}
\end{align}
defined by
\begin{align}
\langle y, \bar{y} \rangle := \int_0^1 (a_x \bar{a}_x + b \bar{b}) dx + \gamma a(1) \bar{a}(1) + \frac{1}{m} \eta \bar{\eta},
\end{align}
where \( y = (a, b, \eta) \) and \( \bar{y} = (\bar{a}, \bar{b}, \bar{\eta}) \) are in \( \mathcal{H} \). Observe that this inner product is based upon the energy of the string (see also (3.1)). For that reason we call the space the energy space \( \mathcal{H} \). The energy space \( \mathcal{H} \) together with the inner product \( \langle \cdot, \cdot \rangle \) is a Hilbert space.

Next, we define the unbounded operator \( A : D(A) \subset \mathcal{H} \to \mathcal{H} \) by
\begin{align}
Ay(t) := \begin{pmatrix}
b \\
apx \\
\gamma a(1) + ap(1) + \frac{\omega}{m}\eta
\end{pmatrix}, \quad y \in D(A),
\end{align}
where
\begin{align}
D(A) := \{ y(t) = (a, b, \eta) \in (H^2[0, 1] \cap \mathcal{V}) \times \mathcal{V} \times \mathbb{R}; \; \eta = mb(1) \}.
\end{align}
Using (4.11) it then follows that (4.6) can be rewritten in the form
\begin{align}
\dot{y} &= Ay, \\
y(0) &= \Phi,
\end{align}
where \( \dot{y} = \frac{dy(t)}{dt} \), and \( \Phi := \begin{pmatrix}
\phi \\
\psi \\
\eta(0)
\end{pmatrix} \).
Theorem 4.1. Operator $A : \mathcal{D}(A) \subset \mathcal{H} \to \mathcal{H}$ defined by (4.11) generates a $C_0$ semigroup of contractions $T(t)$ on the energy space $\mathcal{H}$.

Proof. According to the Lumer-Phillips Theorem (see [2], p. 26), it is sufficient to show that $A$ is an $m$-dissipative operator. First, take any $y = (a, b, \eta) \in \mathcal{D}(A)$ and then a straightforward computation gives

$$
\langle Ay, y \rangle = \int_0^1 (a_x b_x + a_{xx} b) dx + \gamma a(1) \eta - \frac{1}{m} \left[ \gamma a(1) + a_x(1) + \frac{\epsilon}{m} \eta \right]
$$

$$
= a_x b_{||0}^1 + \gamma a(1) \eta - \gamma a(1) \eta - a_x(1) \eta - \frac{\epsilon}{m^2} \eta^2
$$

$$
= - \frac{\epsilon}{m^2} \eta^2 \leq 0.
$$

From (4.15) it follows that the operator $A$ is dissipative. Then we have to prove that the system

$$
(I - A)y = y_0
$$

is uniquely solvable for any given $y_0 = (a_0, b_0, \eta_0) \in \mathcal{H}$. Equation (4.16) is equivalent with

$$
a - b = a_0,
$$

$$
b - a_{xx} = b_0,
$$

$$
\eta + \gamma a(1) + a_x(1) + \frac{\epsilon}{m} \eta = \eta_0.
$$

Eliminating $b$ from (4.17) and (4.18) and using (4.5) we obtain the equation

$$
a - a_{xx} = a_0 + b_0 \in L^2(0, 1),
$$

$$
a(0) = 0,
$$

$$
(m + \epsilon + \gamma)a(1) + a_x(1) = \eta_0 + (\epsilon + m)a_0(1).
$$

Equations (4.20) - (4.22) have a unique solution $a \in H^2(0, 1) \cap V$. From (4.19) the function $\eta$ can be found. By this construction we found that $y = (a, b, \eta) \in \mathcal{D}(A)$. So, the proof of the theorem now follows directly from the Lumer-Phillips Theorem. \[\square\]

If $A$ is a linear operator on $\mathcal{H}$ generating the $C_0$ semigroup $T(t)$ and if the function $y_0$ is in $\mathcal{D}(A)$ then we can show that $T(t)y_0$ is in $\mathcal{D}(A)$. Moreover, we have the following lemma.

Lemma. Let $A$ be the infinitesimal generator of the $C_0$ semigroup $T(t)$. Then for any $f \in \mathcal{D}(A)$ we have $T(t)f \in \mathcal{D}(A)$ and the function

$$
[0, \infty) \ni t \mapsto T(t)f \in \mathcal{H}
$$

is differentiable. In fact,

$$
\frac{d}{dt}T(t)f = AT(t)f = T(t)Af.
$$

Proof. See [3] page 398. \[\square\]

For $y_0 \in \mathcal{D}(A)$ we define

$$
(a, b, \eta) = y(t) := T(t)y_0.
$$

Applying the lemma we find that

$$
a \in C^2 \left( R^+; L^2[0, 1] \right) \cap C \left( R^+; V \cap H^2(0, 1) \right).
$$
So \( y(t) = T(t)y_0 \) is a strong solution of (4.13) - (4.14) for all \( y_0 \in D(A) \). But for \( y_0 \in D(A^2) \), applying the lemma twice we have

\[
\begin{pmatrix}
    a_{tt} \\
    b_{tt} \\
    \eta_{tt}
\end{pmatrix} = A \begin{pmatrix}
    b \\
    a_{xx} \\
    -\gamma a(1) - a_x(1) - \frac{a}{m} \eta
\end{pmatrix}, \tag{4.27}
\]

\[
\begin{pmatrix}
    a_{xx} \\
    b_{xx}
\end{pmatrix} = \frac{a_{xx}}{r}, \tag{4.28}
\]

where \( r = -\gamma b(1) - b_x(1) + \frac{a}{m} a(1) + \frac{a}{m} a_x(1) + \left( \frac{a}{m} \right)^2 \eta \).

From (4.27) - (4.28) and the definition of \( D(A) \) (see (4.12)) we obtain

\[
t \mapsto a(t) \in C^1 \left( \mathbb{R}^+, H^2 \cap V \right), \tag{4.29}
\]

\[
t \mapsto a_{xx} \in V. \tag{4.30}
\]

On the other hand, we also have

\[
t \mapsto a(t) \in C^2 \left( \mathbb{R}^+, V \right). \tag{4.31}
\]

From (4.29) - (4.31), it follows that

\[
a \in C^2 \left( \mathbb{R}^+; V \right) \cap C^1 \left( \mathbb{R}^+; V \cap H^2(0, 1) \right) \cap C \left( \mathbb{R}^+; H^3(0, 1) \cap V \right). \tag{4.32}
\]

So from (4.25) and (4.32), for all \( y_0 \in D(A^2), y(t) = T(t)y_0 \), we have the equivalence between problem (1.1) - (1.5) and problem (4.13) - (4.14). So, the following theorem has now been established.

**Theorem 4.2.** Let \( \Phi \in D(A^2) \), then the initial - boundary value problem (1.1) - (1.5) and the initial value problem (4.13) - (4.14) are equivalent.

Next, we will show that the solution of the initial - boundary value problem (1.1) - (1.5) depends continuously on the initial values. Let \( \tilde{y}(t) \) satisfy (4.13) with the initial values

\[
\tilde{y}(0) = \Phi \text{ where } \Phi = \begin{pmatrix}
\phi \\
\psi \\
\tilde{y}(0)
\end{pmatrix}, \quad (\phi, \psi) \in (C^2[0, 1] \cap V) \times V.
\]

Now, we approximate the difference between \( y(t) \) and \( \tilde{y}(t) \), as follows;

\[
\|y(t) - \tilde{y}(t)\|_H \leq \|T(t)(\Phi - \hat{\Phi})\|_H \leq \|\Phi - \hat{\Phi}\|_H \tag{4.33}
\]

for all \( t \geq 0 \). This means that small differences between the initial values cause small differences between the solution \( y(t) \) and \( \tilde{y}(t) \) for all \( t \geq 0 \).

We observe that if we take \( \phi(x) \in H^3(0, 1), \phi(0) = \phi''(0) = 0 \) and \( \psi(x) \in H^2(0, 1) \cap V \) then we have \( \Phi \) in the domain \( A^2 \). So, we can now formulate the following theorem on the well-posedness of the initial-boundary value problem (1.1) - (1.5).

**Theorem 4.3.** Suppose \( \phi(x) \in H^3(0, 1), \phi(0) = \phi''(0) = 0 \) and \( \psi(x) \in H^2(0, 1) \cap V, \psi(0) = 0 \), then problem (1.1) - (1.5) has a unique and twice continuously differentiable solution for \( x \in [0, 1] \) and \( t \geq 0 \). Moreover, this solution depends continuously on the initial values.

5. The construction of a formal approximation

In this section, an approximation of the solution of the initial-boundary value problem (1.1) - (1.5) will be constructed using a two-timescales perturbation method. If we expand the solution in Taylor series with respect to \( \epsilon \) straightforwardly, that is,

\[
u(x, t) = u_\infty(x, t) + \epsilon u_1(x, t) + \epsilon^2 u_2(x, t) + \epsilon^3 \ldots,
\]

the approximation of the solution of the problem will contain secular terms. From the energy integral in section 3, we know that the solution is bounded. So, the secular terms should be avoided. That is why a two-timescales perturbation method (as described in [12,13]) will be
applied. Using such a two - timescales perturbation method the function $u(x, t)$ is supposed to be a function of $x, t$ and $\tau = \epsilon t$. For that reason, we put

$$u(x, t) = w(x, t; \tau; \epsilon).$$

Using (5.2) the initial - boundary value problem (1.1) - (1.5) becomes

$$(5.3) \quad w_{tt} + 2\epsilon w_{t\tau} + \epsilon^2 w_{\tau\tau} - w_{xx} = 0, \quad 0 < x < 1, \quad t > 0, \quad \tau > 0,$$

$$(5.4) \quad w(0, t; \tau; \epsilon) = 0, \quad t > 0, \quad \tau > 0,$$

$$(5.5) \quad mw_{tt}(1, t) + \gamma w(1, t) + w_x(1, t) = -\epsilon(w_v(1, t) + 2mw(1, t)), \quad t > 0, \quad \tau > 0,$$

$$(5.6) \quad w(x, 0, 0; \epsilon) = \phi(x; \epsilon), \quad 0 < x < 1,$$

$$(5.7) \quad w_t(x, 0, 0; \epsilon) + \epsilon w_{\tau x}(x, 0, 0; \epsilon) = \psi(x; \epsilon), \quad 0 < x < 1,$$

with

$$\phi(x) \in C^5([0, 1]; \mathbb{R}), \quad \psi(x) \in C^4([0, 1]; \mathbb{R}),$$

and

$$(5.9) \quad \phi(0) = \phi''(0) = \phi'''(0) = \psi(0) = \psi''(0) = 0,$$

$$(5.10) \quad m\phi''(1) + \gamma \phi(1) + \phi'(1) = -\epsilon\psi(1),$$

$$(5.11) \quad m\phi''(1) + \gamma \phi''(1) + \phi'''(1) = -\epsilon\psi''(1),$$

$$(5.12) \quad m\psi''(1) + \gamma \psi(1) + \psi'(1) = -\epsilon\phi''(1).$$

Using a two - timescales perturbation it is assumed that $w(x, \tau_1, \tau_2; \epsilon)$ can be approximated by the formal expansion

$$u_\omega(x, t, \tau) + \epsilon u_1(x, t, \tau) + \epsilon^2 u_2(x, t, \tau) + \epsilon^3 \cdots.$$ From (5.10) - (5.12), it is reasonable to expand the functions $\phi(x; \epsilon)$ and $\psi(x; \epsilon)$ in Fourier series, that is,

$$(5.14) \quad \phi(x) = \phi_0(x) + \epsilon \phi_1(x) + \cdots,$$

$$(5.15) \quad \psi(x) = \psi_0(x) + \epsilon \psi_1(x) + \cdots.$$ Substituting (5.13) into (5.3) - (5.5) and (5.14) - (5.15) into (5.6) - (5.7), and after equating the coefficients of like powers in $\epsilon$, it follows that $u_\omega$ has to satisfy

$$(5.16) \quad u_{\omega tt} - u_{\omega xx} = 0, \quad 0 < x < 1, \quad t > 0, \quad \tau > 0,$$

$$(5.17) \quad u_{\omega}(0, t; \tau) = 0, \quad t > 0, \quad \tau > 0,$$

$$(5.18) \quad m\omega_{tt}(1, t) + \gamma \omega(1, t) + \omega_x(1, t) = 0, \quad t > 0, \quad \tau > 0,$$

$$(5.19) \quad \omega_0(x, 0, 0) = \phi_0(x), \quad 0 < x < 1,$$

$$(5.20) \quad \omega_0(x, 0, 0) = \psi_0(x), \quad 0 < x < 1.$$ with

$$(5.21) \quad \phi_0(0) = \phi''_0(0) = \phi'''_0(0) = \psi_0(0) = \psi''_0(0) = 0,$$

$$(5.22) \quad m\phi''(1) + \gamma \phi(1) + \phi'(1) = 0,$$

$$(5.23) \quad m\phi''(1) + \gamma \phi''(1) + \phi'''(1) = 0,$$

$$(5.24) \quad m\psi''(1) + \gamma \psi(1) + \psi'(1) = 0.$$ The solution of (5.16) - (5.20) follows from section 2, yielding

$$u_\omega(x, t, \tau) = \sum_{n=1}^{\infty} \left( A_n(\tau) \sin(\sqrt{\lambda_n}t) + B_n(\tau) \cos(\sqrt{\lambda_n}t) \right) \sin(\sqrt{\lambda_n}x).$$
where $A_n(0)$ and $B_n(0)$ are given by

$$A_n(0) = \frac{\int_0^1 [1 + m\delta(x - 1)]\phi(x)\sin(\sqrt{\lambda_n}x)dx}{\int_0^1 [1 + m\delta(x - 1)]\sin^2(\sqrt{\lambda_n}x)dx},$$

and $B_n(0)$ is given by

$$B_n(0) = \frac{1}{\sqrt{\lambda_n}} \int_0^1 [1 + m\delta(x - 1)]\psi(x)\sin(\sqrt{\lambda_n}x)dx,$$

and where $\lambda_n$ is given by (2.19).

Using (5.8) and (5.21) - (5.24) we obtain the following inequalities

$$|A_n(0)| \leq \frac{2C_1}{\lambda_n^{3/2}},$$

$$|B_n(0)| \leq \frac{2C_2}{\lambda_n^{3/2}},$$

where $C_2$ and $C_1$ are given by

$$C_2 = \max_{1 \leq n < \infty} \left\{ \left| \frac{\gamma}{\sqrt{\lambda_n}} \phi_0^{(iv)}(1) \sin(\sqrt{\lambda_n}) - \int_0^1 \phi_0^{(iv)}(x) \cos(\sqrt{\lambda_n}x)dx \right| \right\},$$

and

$$C_1 = \max_{1 \leq n < \infty} \left\{ \left| - (\gamma \psi_0'(1) + \psi_0''(1)) \sin(\sqrt{\lambda_n}) + \int_0^1 \psi_0'(x) \sin(\sqrt{\lambda_n}x)dx \right| \right\},$$

respectively.

The $O(\epsilon)$ problem for $u_1$ is given by

$$u_{1tt} - u_{1xx} = -2u_{otx}, \quad 0 < x < 1, \quad t > 0,$$

$$u_1(0, t, \tau) = 0, \quad t > 0, \quad \tau > 0,$$

$$mu_{1t}(1, t, \tau) + \gamma u_1(1, t, \tau) + u_{1x}(1, t, \tau) = -2mu_{ox}(1, t, \tau) - u_o(1, t, \tau), \quad t > 0, \quad \tau > 0,$$

$$u_1(x, 0, 0) = \phi_1(x), \quad 0 < x < 1,$$

$$u_{1x}(x, 0, 0) = \psi_1(x) - u_{ox}(x, 0, 0), \quad 0 < x < 1.$$

with

$$\phi_1(0) = \phi_1''(0) = \phi_1'''(0) = \psi_0(0) = \psi_1''(0) = 0,$$

$$m\phi_1'(1) + \gamma \phi_1(1) + \phi_1''(1) = -\psi_0(1),$$

$$m\phi_1'(1) + \gamma \phi_1''(1) + \phi_1'''(1) = -\psi_1''(1),$$

and

$$m\psi_1'(1) + \gamma \psi_1(1) + \psi_1''(1) = -\phi_0''(1).$$

To solve (5.32) - (5.36) the eigenfunction expansion approach will be used. Making boundary conditions homogeneous is the usual way to solve initial-boundary value problems when the inhomogeneous boundary conditions are of classical type (that is, are of Dirichlet, Neumann, or of Robin type). For the non-classical boundary condition at $x = 1$ this approach turns out to be not applicable. When we apply the eigenfunction expansion to solve the initial-boundary value problem (5.32) - (5.36) the left-hand side of (5.32) at $x = 1$ and that of (5.34) are of the same form. So, to solve the problem correctly the right-hand side of (5.32) at $x = 1$, and that of (5.34) should match, that is, should be proportional. To obtain this matching we introduce the following transformation

$$u_1(x, t; \tau) = xg(t, \tau) + v(x, t, \tau).$$
Substituting (5.41) into (5.32) and (5.34) we obtain

\begin{align}
(5.42) & \quad v_{tt} - v_{xx} = -2u_{o \alpha r} - x g_{tt}, \quad 0 < x < \pi, \ t > 0, \\
(5.43) & \quad v(0, t, \tau) = 0, \ t > 0, \\
(5.44) & \quad mv_{tt}(1, t, \tau) + \gamma v(1, t, \tau) + v_x(1, t, \tau) = -2mu_{o \alpha r}(1, t, \tau) \\
(5.45) & \quad v(x, 0, 0) = \phi_1(x) - x g(0, 0), \ 0 < x < \pi, \\
(5.46) & \quad v_t(x, 0, 0) = \psi_1(x) - u_{o \alpha}(x, 0, 0) - x g_t(0, 0), \ 0 < x < \pi.
\end{align}

To solve (5.42) - (5.46) \( v(x, t, \tau) \) is written in the eigenfunction expansion

\begin{equation}
(5.47) \quad v(x, t, \tau) = \sum_{n=1}^{\infty} v_n(t, \tau) \sin(\sqrt{\lambda_n} x).
\end{equation}

Substituting (5.47) into (5.42) and (5.44) and taking the limit for \( x = 1 \) we obtain

\begin{equation}
(5.48) \quad \sum_{n=1}^{\infty} \left( (mv_{nt}(t, \tau) + \gamma v_n(t, \tau)) \sin(\sqrt{\lambda_n} x) + \sqrt{\lambda_n} v_n(t, \tau) \cos(\sqrt{\lambda_n} x) \right) = -2mu_{o \alpha r}(1, t, \tau)
\end{equation}

and

\begin{equation}
(5.49) \quad -u_{o \alpha}(1, t, \tau) - mg_{tt}(t, \tau) - (\gamma + 1) g(t, \tau)
\end{equation}

respectively. From (2.19) it follows that \( m \lambda_n = \gamma + \sqrt{\lambda_n} \cot(\sqrt{\lambda_n}) \), and so \( m \) times the left-hand side of (5.48) is equal to that of (5.49). And so, \( m \) times the right-hand side of (5.48) should be equal to that of (5.49). It then follows that

\begin{equation}
(5.50) \quad \Rightarrow \quad g(t, \tau) = -\frac{1}{\gamma + 1} u_{o \alpha}(1, t, \tau).
\end{equation}

The initial - boundary value problem (5.42) - (5.46) now becomes

\begin{align}
(5.51) & \quad v_{tt} - v_{xx} = -2u_{o \alpha r} + \frac{1}{\gamma + 1} \sum_{n=1}^{\infty} v_n(t, \tau), \ 0 < x < 1, \ t > 0, \\
(5.52) & \quad v(0, t, \tau) = 0, \ t > 0, \\
(5.53) & \quad mv_{tt}(1, t, \tau) + \gamma v(1, t, \tau) + v_x(1, t, \tau) = -2mu_{o \alpha r}(1, t, \tau) + m \frac{1}{\gamma + 1} u_{o \alpha r}(1, t, \tau), \ t > 0, \\
(5.54) & \quad v(x, 0, 0) = \phi_1(x) + \frac{\psi_1(x)}{\gamma + 1} x, \ 0 < x < \pi, \\
(5.55) & \quad v_t(x, 0, 0) = \psi_1(x) - u_{o \alpha}(x, 0, 0) + \frac{\phi_1'(x)}{\gamma + 1} x, \ 0 < x < \pi.
\end{align}

It should be observed that if \( m \) is equal to zero then the boundary condition at \( x = 1 \) becomes a classical boundary condition. From (5.53) it can readily be seen that in that case the boundary condition (5.34) at \( x = 1 \) becomes an homogeneous one after the transformation (5.41). When we expand \( x \) in a Fourier series, that is,

\begin{equation}
(5.56) \quad x = \sum_{n=1}^{\infty} c_n \sin(\sqrt{\lambda_n} x),
\end{equation}

it can be shown that
where \( c_n \) is given by

\[
(5.57) \quad c_n = \frac{\int_0^1 x[1 + m\delta(x - 1)]\sin(\sqrt{\lambda_n}x)dx}{\int_0^1 [1 + m\delta(x - 1)]\sin^2(\sqrt{\lambda_n}x)dx} = \frac{2(\gamma + 1)\sin(\sqrt{\lambda_n})}{\lambda_n + (m\lambda_n + \gamma)\sin^2(\sqrt{\lambda_n})}
\]

the initial-boundary value problem (5.51) - (5.55) can now be solved by substituting (5.47) into the partial differential equation (5.51), yielding

\[
(5.58) \quad v_{ntt} + \lambda_n v_n = \left(2\sqrt{\lambda_n} A'_n + \frac{c_n}{\gamma + 1} \lambda_n^{3/2} \sin(\sqrt{\lambda_n})A_n \sin(\sqrt{\lambda_n}t)\right)
\]

\[-(2\sqrt{\lambda_n} B'_n + \frac{c_n}{\gamma + 1} \lambda_n^{3/2} \sin(\sqrt{\lambda_n})B_n \cos(\sqrt{\lambda_n}t))
\]

\[+ \frac{c_n}{\gamma + 1} \sum_{p \neq n} \infty \lambda_p^{3/2} \sin(\sqrt{\lambda_p})(A_p \sin(\sqrt{\lambda_p}t) - B_p \cos(\sqrt{\lambda_p}t)).\]

Observe that \( v(x, t, \tau) \) now automatically satisfies the boundary conditions at \( x = 0 \) and \( x = 1 \). In order to remove secular terms, it now easily follows from (5.58) that \( A_n \) and \( B_n \) have to satisfy

\[
(5.59) \quad A'_n + \frac{c_n}{2(\gamma + 1)} \lambda_n \sin(\sqrt{\lambda_n})A_n = 0,
\]

\[
(5.60) \quad B'_n + \frac{c_n}{2(\gamma + 1)} \lambda_n \sin(\sqrt{\lambda_n})B_n = 0.
\]

Using (2.19) we define

\[
(5.61) \quad \alpha_n = \frac{c_n}{2(\gamma + 1)} \lambda_n \sin(\sqrt{\lambda_n}) = \frac{\lambda_n \sin^2(\sqrt{\lambda_n})}{\lambda_n + (m\lambda_n + \gamma)\sin^2(\sqrt{\lambda_n})} > 0.
\]

The solution of (5.59) - (5.60) is given by

\[
(5.62) \quad A_n(\tau) = A_n(0) \exp(-\alpha_n \tau),
\]

\[
(5.63) \quad B_n(\tau) = B_n(0) \exp(-\alpha_n \tau).
\]

From (5.28) - (5.29) and (5.61) - (5.63) it follows that the infinite series representation (5.25) for \( u_\circ \) is twice continuously differentiable with respect to \( x \) and \( t \), and infinitely many times with respect to \( \tau \). From (2.19) it follows that \( \sqrt{\lambda_n} \to (n - 1)\pi \) as \( n \to \infty \). So, \( \alpha_n \) tends to 0 as \( n \) tends to \( \infty \). From (5.62) and (5.63) it then follows that \( u_\circ \) is stable but not uniform. From (5.58) \( v_n(t, \tau) \) can now be determined, yielding

\[
(5.64) \quad v_n(t, \tau) = D_n(\tau) \cos(\sqrt{\lambda_n}t) + E_n(\tau) \sin(\sqrt{\lambda_n}t)
\]

\[+ \sum_{p \neq n} \infty \frac{1}{\gamma + 1} \lambda_p^{3/2} \sin(\sqrt{\lambda_p})(-A_p(\tau) \sin(\sqrt{\lambda_p}t) + B_p(\tau) \cos(\sqrt{\lambda_p}t)),\]
where \( D_n(\tau) \) and \( E_n(\tau) \) are still arbitrary functions which can be used to avoid secular terms in \( u_2(x, t, \tau) \). From (5.54) and from (5.55) it follows that

\[
D_n(0) = \frac{1}{\beta_n} \int_0^1 [1 + m\delta(x - 1)] \left[ \phi_1(x) + \frac{p(x_1)}{\gamma + 1} \right] \sin(\sqrt{\lambda_n}x) dx \]

\[
- \frac{c_n}{\gamma + 1} \sum_{p \neq n} \frac{\lambda_p^{3/2}}{\lambda_p - \lambda_n} \sin(\sqrt{\lambda_p}) B_p(0),
\]

(5.66)

\[
\sqrt{\lambda_n} E_n(0) = \frac{1}{\beta_n} \int_0^1 [1 + m\delta(x - 1)] \left[ \psi_1(x) + \frac{\phi''(1)}{\gamma + 1} \right] \sin(\sqrt{\lambda_n}x) dx
\]

\[
+ \alpha_n B_n(0) + \frac{c_n}{\gamma + 1} \sum_{p \neq n} \frac{\lambda_p^{3/2}}{\lambda_p - \lambda_n} \sin(\sqrt{\lambda_p}) A_n(0),
\]

where \( \beta_n = \int_0^1 [1 + m\delta(x - 1)] \sin^2(\sqrt{\lambda_n}x) dx = \frac{1}{2} \left[ 1 + \frac{\sin^2(\sqrt{\lambda_n})}{\lambda_n} \right] \geq \frac{1}{2} \). Elementary it can be shown that \( |D_n(0)| \leq \frac{C_2}{\lambda_n} \) and \( E_n(0) \leq \frac{C_3}{\lambda_n} \), where \( C_2 \) and \( C_3 \) are constants.

The solution \( u_1(x, t, \tau) \) of (5.32) - (5.36) now easily follows from (5.41), (5.47), (5.50), and (5.64), yielding

\[
(5.67) \quad u_1(x, t, \tau) = \sum_{n=1}^{\infty} \left( v_n(t, \tau) + \frac{c_n}{\gamma + 1} \sum_{p=1}^{\infty} H_p(t, \tau) \right) \sin(\sqrt{\lambda_n}x),
\]

where \( H_p(t, \tau) = \sqrt{\lambda_p} \sin(\sqrt{\lambda_p}x) \left( B_p(\tau) \sin(\sqrt{\lambda_p}t) - A_p(\tau) \cos(\sqrt{\lambda_p}t) \right) \), where \( v_n \) is given by (5.64), where \( A_n(\tau) \) and \( B_n(\tau) \) are given by (5.62) and (5.63), and where \( c_n \) is given by (5.57).

It should be observed that \( u_1(x, t, \tau) \) still contains infinitely many undetermined functions \( D_n(\tau) \) and \( E_n(\tau) \), \( n = 1, 2, 3, \cdots \). These functions can be used to avoid secular terms in the function \( u_2(x, t, \tau) \). At this moment, however, we are not interested in the higher order approximations. For that reason we will take \( D_n(\tau) = D_n(0) \) and \( E_n(\tau) = E_n(0) \). So far we have constructed a formal approximation \( \bar{u}(x, t) = u_0(x, t, \tau) + \epsilon u_1(x, t, \tau) \) of \( u(x, t) \), where \( u_0(x, t, \tau) \) and \( u_1(x, t, \tau) \) are twice continuously differentiable with respect to \( x \) and \( t \), and infinitely many times with respect to \( \tau \).

6. On the asymptotic validity of formal approximations

In this section, we study the asymptotic validity of formal approximations on \( 0 \leq t \leq L_0 \epsilon^{-1} \) and \( 0 \leq x \leq 1 \), where \( L_0 \) is an \( \epsilon \)-independent constant. We will show that a formal approximation of the solution is indeed an asymptotic approximation if the approximation satisfies the PDE, and the ICs and BCs up to some, specified order in \( \epsilon \). In section 5 we have constructed the function

\[
(6.1) \quad \bar{u}(x, t) = u_0(x, t, \tau) + \epsilon u_1(x, t, \tau).
\]

This function is a so-called formal approximation of the solution and this function satisfies the following initial-boundary value problem

\[
(6.2) \quad \bar{u}_{tt} - \bar{u}_{xx} = \epsilon^2 F(x, t; \epsilon), \quad 0 < x < 1, \ t > 0,
\]

\[
(6.3) \quad \bar{u}(0, t) = 0, \quad t \geq 0,
\]

\[
(6.4) \quad m\bar{u}_{tt}(1, t) + \gamma \bar{u}(1, t) + \bar{u}_x(1, t) + \epsilon \bar{u}_t(1, t) = \epsilon^2 R(t, \tau; \epsilon), \ t \geq 0,
\]

\[
(6.5) \quad \bar{u}(x, 0) = \phi_0(x) + \epsilon \phi_1(x), \quad 0 < x < 1,
\]

\[
(6.6) \quad \bar{u}_t(0, 0) = \psi_0(x) + \epsilon \psi_1(x) + \epsilon^2 u_1(x, 0, 0), \quad 0 < x < 1,
\]
where

\[
F(x, t; \epsilon) = u_{0, x}(x, t, \tau) + 2u_{1, x}(x, t, \tau) + \epsilon u_{1, x}(x, t, \tau),
\]

\[
R(t, \tau; \epsilon) = m u_{0, x}(1, t, \tau) + 2 m u_{1, x}(1, t, \tau) + u_{x}(1, t, \tau) + u_{1}(1, t, \tau) + c m u_{1, \tau}(1, t, \tau) + \epsilon u_{1, \tau}(1, t, \tau),
\]

To prove the asymptotic validity of \( \hat{u}(x, t, \tau) \) we define some auxiliary functions,

\[
\hat{a}(t) = \hat{a}(\bullet, t),
\]

\[
\hat{b}(t) = \hat{u}_t(\bullet, t),
\]

\[
\hat{\eta}(t) = m \hat{u}_t(1, t).
\]

We also denote \( \hat{a}, \hat{b} \) and \( \hat{\eta} \) for \( \hat{a}(t), \hat{b}(t) \) and \( \hat{\eta}(t) \), respectively. By differentiating these functions with respect to \( t \) we obtain

\[
\begin{pmatrix}
\hat{a}_t \\
\hat{b}_t \\
\hat{\eta}_t
\end{pmatrix} = \begin{pmatrix}
\hat{b} \\
-\gamma \hat{a}(1) - \hat{a}_x(1) - \frac{\alpha}{m} \hat{\eta}
\end{pmatrix} + \epsilon^2 \begin{pmatrix}
0 \\
F(\bullet, t; \epsilon)
\end{pmatrix}.
\]

We also define the same operator \( A \) as in section 4, i.e.

\[
A \hat{\eta} = \begin{pmatrix}
\hat{b} \\
-\gamma \hat{a}(1) - \hat{a}_x(1) - \frac{\alpha}{m} \hat{\eta}
\end{pmatrix},
\]

where \( \hat{\eta} = \begin{pmatrix} \hat{a} \\ \hat{b} \\ \hat{\eta} \end{pmatrix} \), and (6.10) then becomes

\[
\frac{d \hat{\eta}}{dt} = A \hat{\eta} + \epsilon^2 \Theta(t),
\]

\[
\hat{\eta}(0) = \Phi,
\]

where \( \Theta(t) = \begin{pmatrix} 0 \\ F(\bullet, t; \epsilon) \end{pmatrix} \), and \( \Phi = \begin{pmatrix} \phi_2 + \epsilon \phi_3 + \cdots \\ m (u_{1, t}(1, 0, 0) - \psi_2(1) - \epsilon \psi_3(1) + \cdots) \end{pmatrix} \).

From the convergence and differentiability properties of the infinite series representations for \( u_0 \) and \( u_1 \) it follows that \( \Theta \) and \( \Phi - \Phi \) are bounded, that is, there are two constants \( M_0 \) and \( M_1 \) such that

\[
\| \Theta(t) \|_\mathcal{H} \leq M_0,
\]

\[
\| \Phi - \Phi \|_\mathcal{H} \leq \epsilon^2 M_1.
\]

The solution of the initial value problem (6.12) - (6.13) is given by

\[
\hat{\eta}(t) = T(t, \Phi) + \epsilon^2 \int_0^t T(t - s) \Theta(s) ds,
\]

where \( T(t) \) is defined as in section 4. For \( 0 \leq t \leq L_0 \epsilon^{-1} \) and \( 0 \leq x \leq 1 \), we can now estimate the difference between \( \eta \) and \( \hat{\eta} \)

\[
\| \eta(t) - \hat{\eta}(t) \|_\mathcal{H} \leq \epsilon^2 M_1 + \epsilon^2 M_0 t \leq \epsilon (M_1 + L_0 M_0).
\]

We can conclude from (6.17) that \( \eta(t) - \hat{\eta}(t) = O(\epsilon) \) on a timescale of order \( \frac{1}{\epsilon} \). From this it easily follows that \( u(x, t) = u_0(x, t, \tau) + \epsilon u_1(x, t, \tau) = O(\epsilon) \) and \( u(x, t) = u_0(x, t, \tau) = O(\epsilon) \) on \( 0 \leq t \leq L_0 \epsilon^{-1} \) and \( 0 \leq x \leq 1 \). And so we obtained the asymptotic validity of the formal approximations.
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7. Conclusions

In this paper an initial - boundary value problem for a weakly damped string has been considered. It can be shown that (using a semigroup approach) the initial-boundary value problem (1.1) - (1.5) is well-posed for $0 \leq x \leq 1$ and $t \geq 0$. Using an energy integral it can also be shown that the solution is bounded. The construction of the approximation is far from being elementary. For instance it is not possible to solve (5.32) - (5.36) in the classical way by making the boundary condition at $x = 1$ homogeneous. This is due to the non-classical boundary condition at $x = 1$. It can only be done by balancing or matching the right-hand side of (5.32) and that of (5.34) by transforming $u$ in an appropriate way. It also should be noted that the way to solve the wave equation with a non-classical boundary condition (using the eigenfunction expansion as we have done in section 5) is an extension of the classical way to solve such problem. Finally, we proved that the formal approximation is an asymptotic one on a time-scale of order $\epsilon^{-1}$. Although we did not consider external forces (leading to an inhomogeneous PDE) these problems can be solved in a similar way using the balancing or matching procedure as given in section 5. Actually by considering (5.32) - (5.36) we have solved an inhomogeneous problem. The results presented in this paper most likely can be extended to weakly nonlinear pdes with non-classical boundary conditions.

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